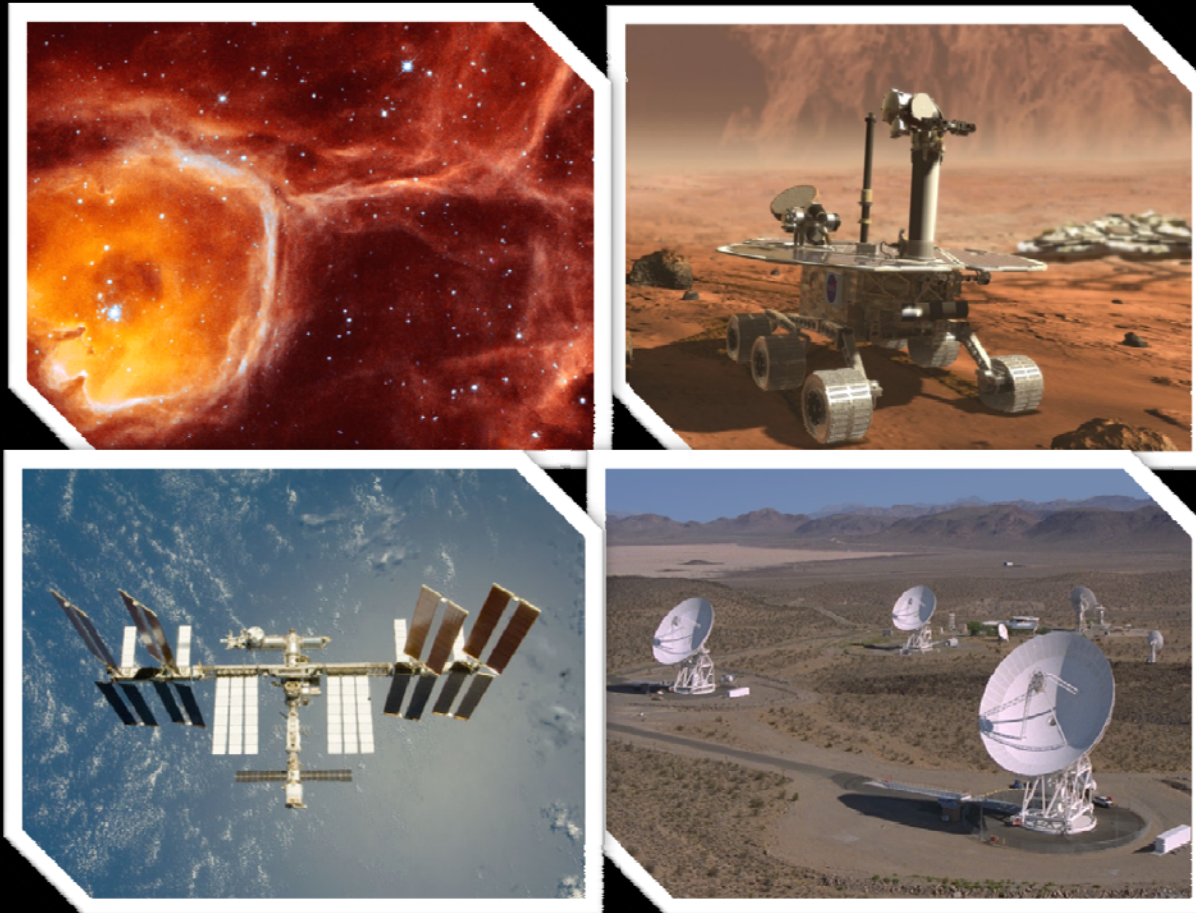


SBIR Technology Applications to Space Communications and Navigation (SCaN)



Phil Liebrecht, Assistant Deputy Associate Administrator
Space Communications and Navigation
August 26, 2010



Outline

- SCaN Overview
- SCaN Architecture
 - Near Earth Domain
 - Lunar Network
 - Mars and Other Deep Space Capabilities
 - Ground Network - Integrated Services Portal
- SCaN Technology Development

Background

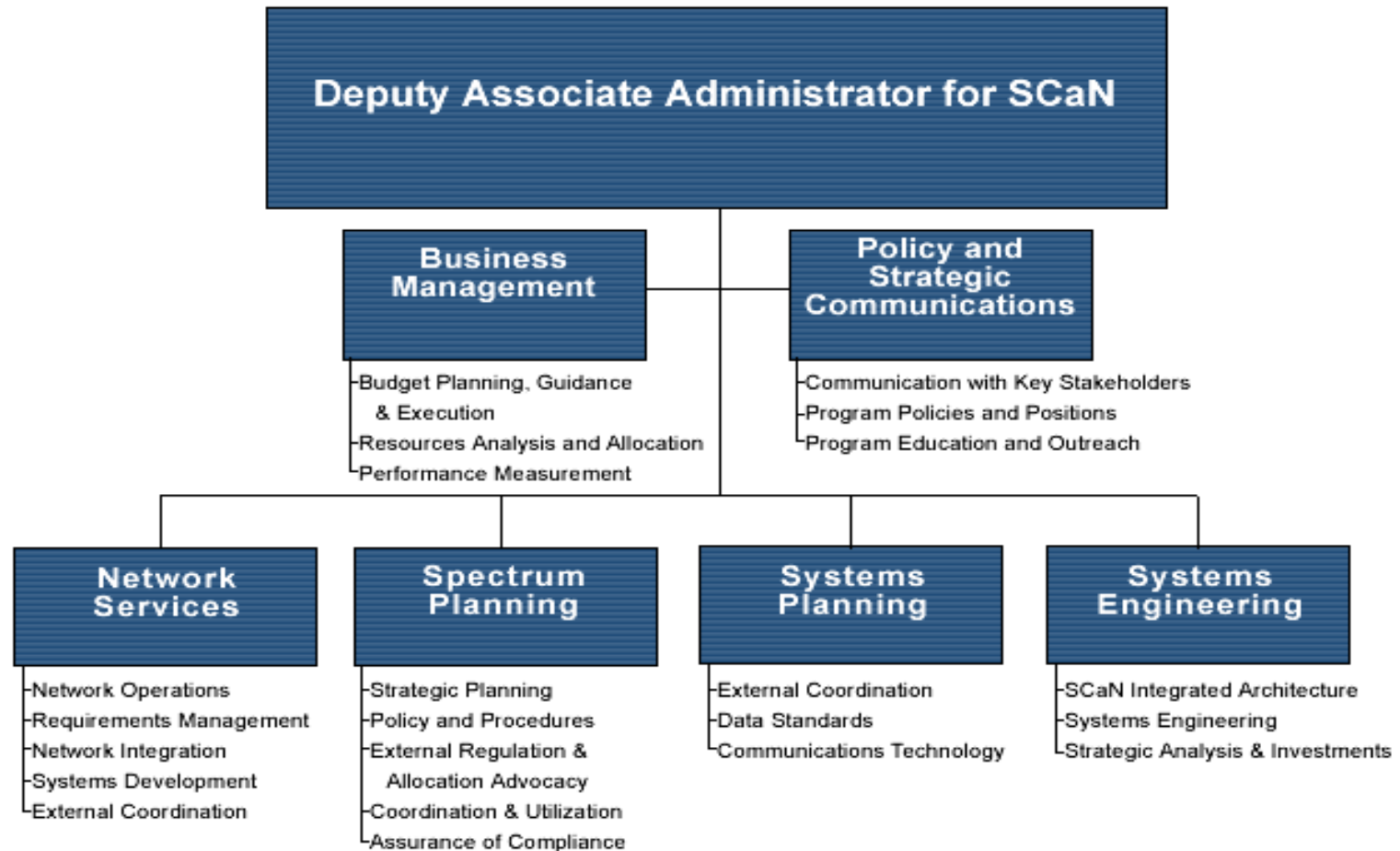
- In 2006, NASA Administrator assigned roles and responsibilities for the Agency's space communications and tracking assets to the SCaN Office.
- This mandate centralized the management of NASA's space communications and navigation networks: the Near Earth Network (NEN), the Space Network (SN), and the Deep Space Network (DSN).
- In a September 2007 memo, the Associate Administrator described the concept of an integrated network architecture.
- The new SCaN integrated network architecture is intentionally capability-driven and will continue to evolve as NASA makes key decisions involving technological feasibility, mission communication needs, and funding.

NASA Level 0 Requirements (Baselined on January 28, 2010)

- SCaN shall develop a unified space communications and navigation network infrastructure capable of meeting both robotic and human exploration mission needs.
- SCaN shall implement a networked communication and navigation infrastructure across space.
- SCaN's infrastructure shall provide the highest data rates feasible for both robotic and human exploration missions.
- SCaN shall assure data communication protocols for Space Exploration missions are internationally interoperable.
- SCaN shall provide the end space communication and navigation infrastructure for Lunar and Mars surfaces.
- SCaN shall provide communication and navigation services to enable Lunar and Mars human missions.
- SCaN shall continue to meet its commitments to provide space communications and navigation services to existing and planned missions.

SCaN Organization Chart

Space Communications and Navigation (SCaN) Office



SCaN Network

Crewed Missions



Sub-Orbital Missions



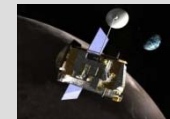
Earth Science Missions



Space Science Missions



Lunar Missions



Solar System Exploration



- DSN
- NEN/NASA
- NEN/Commercial
- NEN/Partner
- SN

Alaska
Satellite
Facility
Fairbanks,
Alaska



Partner Station:
Gilmore Creek, Alaska



USN Alaska
Poker Flat &
North Pole, Alaska



Madrid Complex
Madrid, Spain



Kongsberg Satellite
Services (KSAT)
Svalbard, Norway



Swedish Space Corp. (SSC)
Kiruna, Sweden



German
Space
Agency (DLR)
Weilheim,
Germany



Goldstone Complex
Fort Irwin, California



USN Hawaii
South Point, Hawaii



White Sands
Ground Station
White Sands,
New Mexico



White Sands Ground Terminals
White Sands, New Mexico

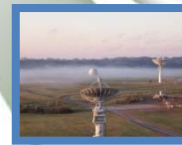
Merritt Island
Launch Annex
Merritt Island, Florida



USN Chile
Santiago, Chile



Wallops Ground
Station
Wallops, Virginia



McMurdo Ground Station
McMurdo Base, Antarctica



Guam Remote Ground Terminal
Guam, Marianna Islands



USN Australia
Dongara, Australia



Canberra Complex
Canberra, Australia



Satellite Applications Center
Hartebeesthoek, Africa





SCaN Architecture

Architectural Goal and Challenges

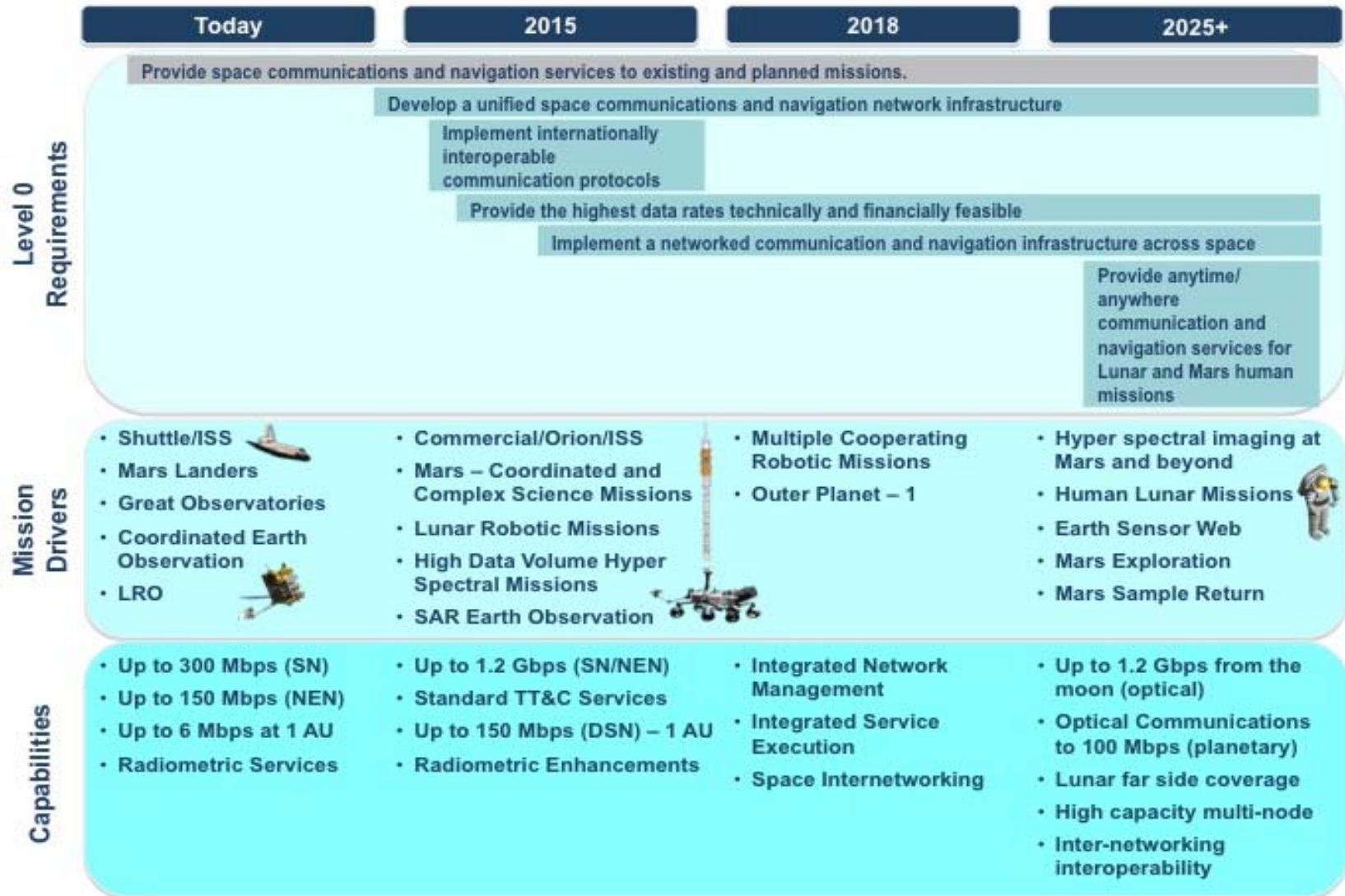
Goal

To detail the high level SCaN integrated network architecture, its elements, architectural options, views, and evolution until 2025 in response to NASA's key driving requirements and missions. The architecture is a framework for SCaN system evolution and will guide the development of program requirements and designs.

Challenges

- Forming an **integrated** network from three pre-existing individual networks
- Resource constraints
- Addressing **requirement**-driven, **capability**-driven, and **technology**-driven approaches **simultaneously**
- **Interoperability** with U.S. and foreign spacecraft and networks
- **Uncertainty** in timing and nature of future communications mission **requirements**
- Requirements for **support** of missions already in **operation**, as well as those to which support commitments have already been made
- Changes in high level requirements and direction

Key Requirements, Mission Drivers, and Capabilities Flowdown



SCaN Current Networks

The current NASA space communications architecture embraces three operational networks that collectively provide communications services to supported missions using space-based and ground-based assets

Near Earth Network

and partner ground stations and integration systems providing space communications and tracking services to orbital and suborbital missions

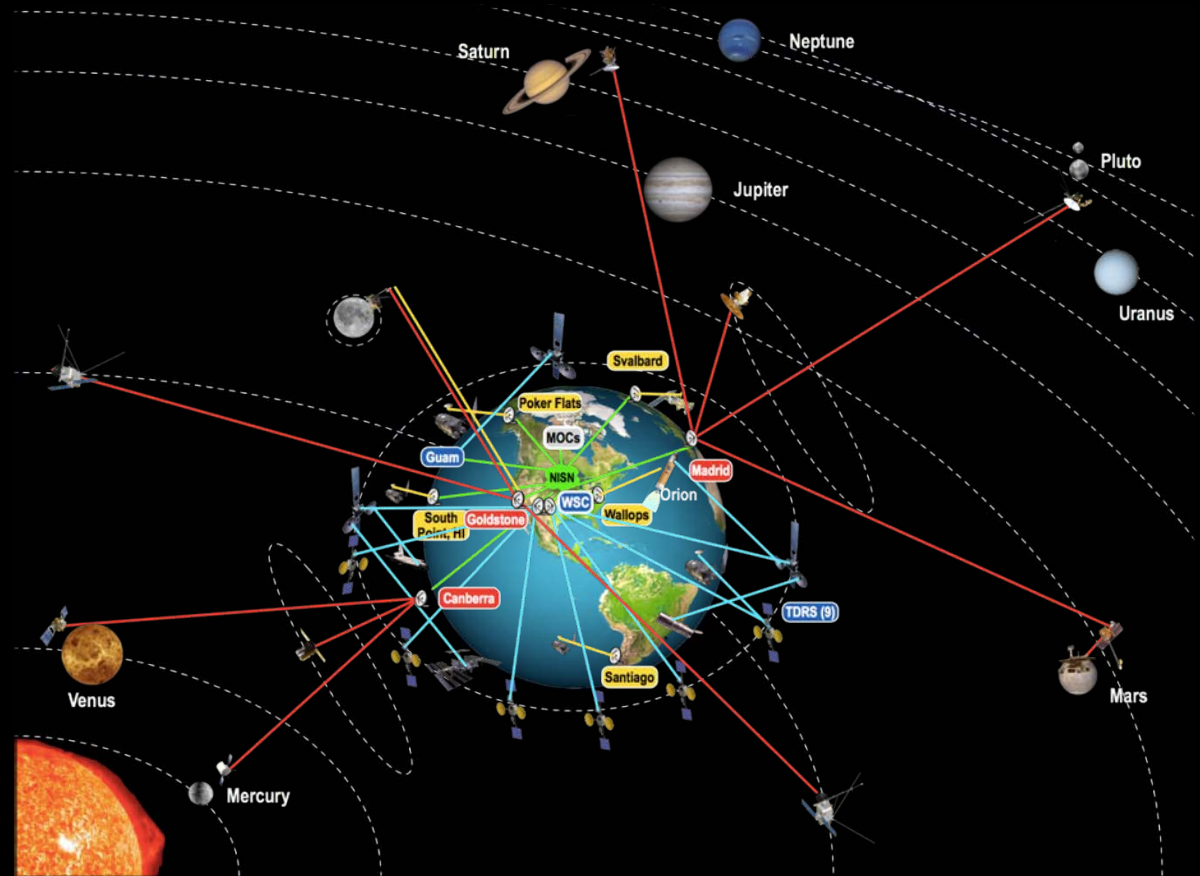
Space Network

geosynchronous relays (TDRSS) and associated ground systems

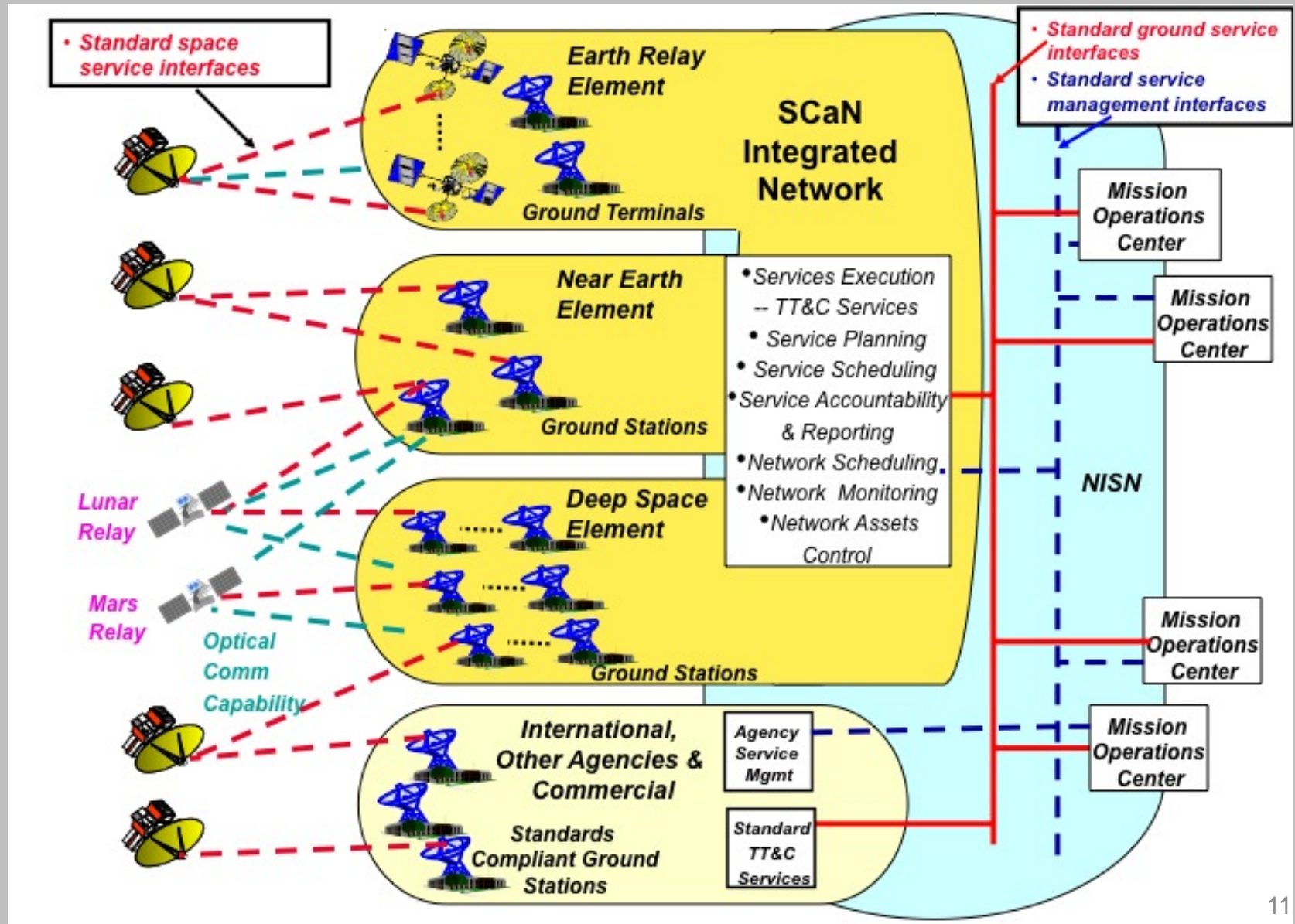
Deep Space Network

spaced around the world providing continuous coverage of satellites from Earth Orbit (GEO) to the edge of our solar system

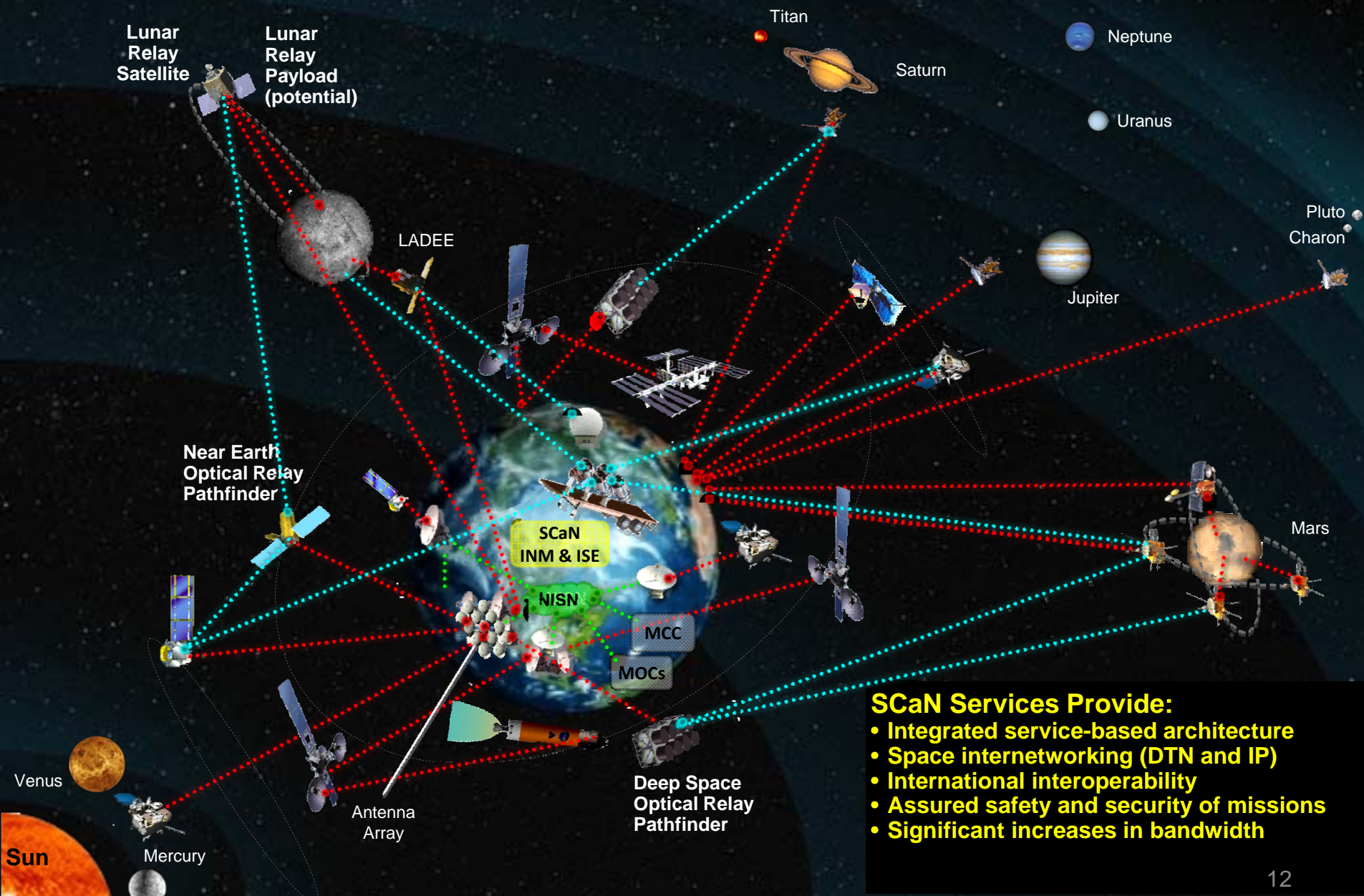
NASA Integrated Services Network (NISN) - not part of SCaN; provides terrestrial connectivity



SCaN Integrated Network Service Architecture



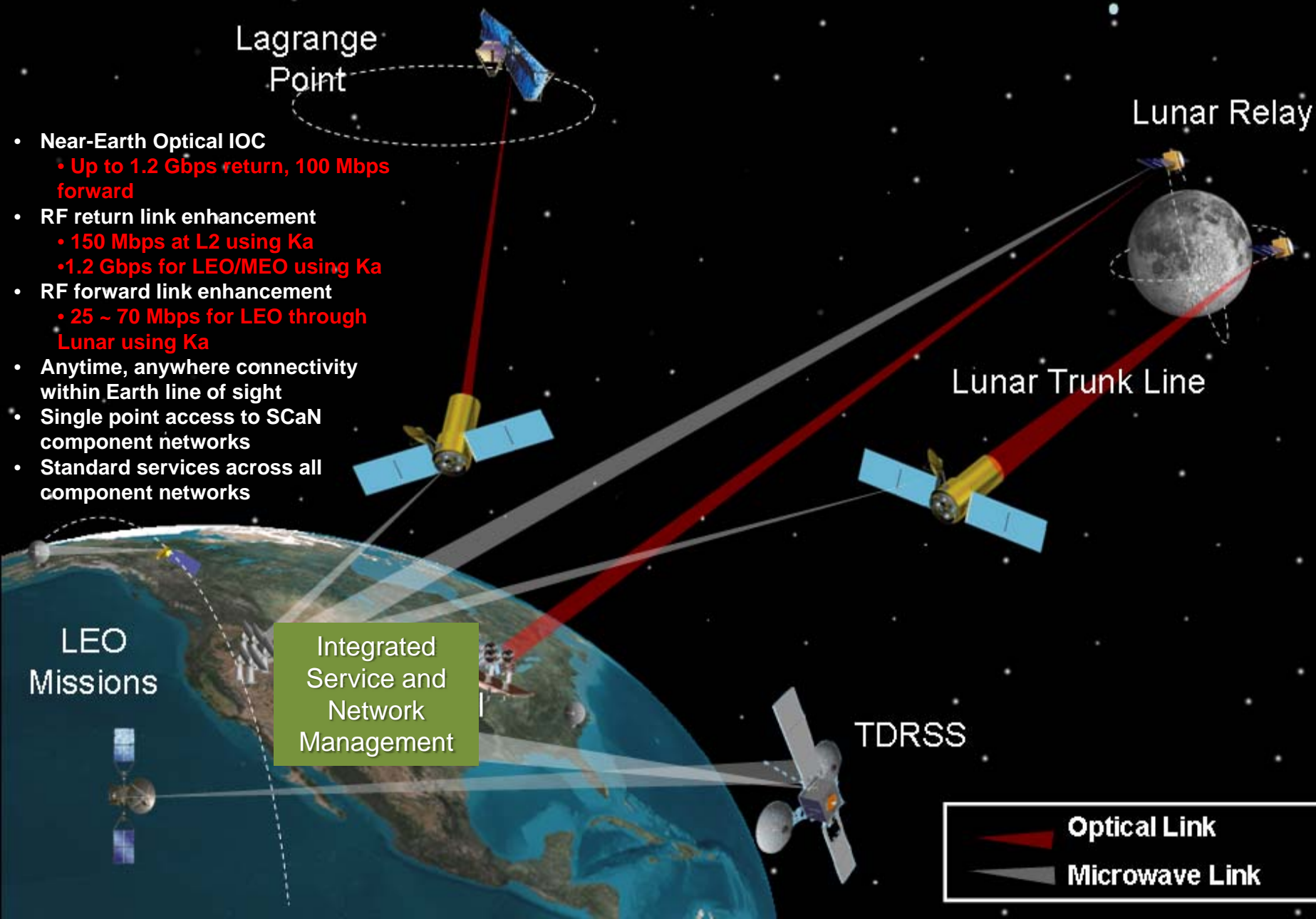
SCaN Notional Integrated Communication Architecture



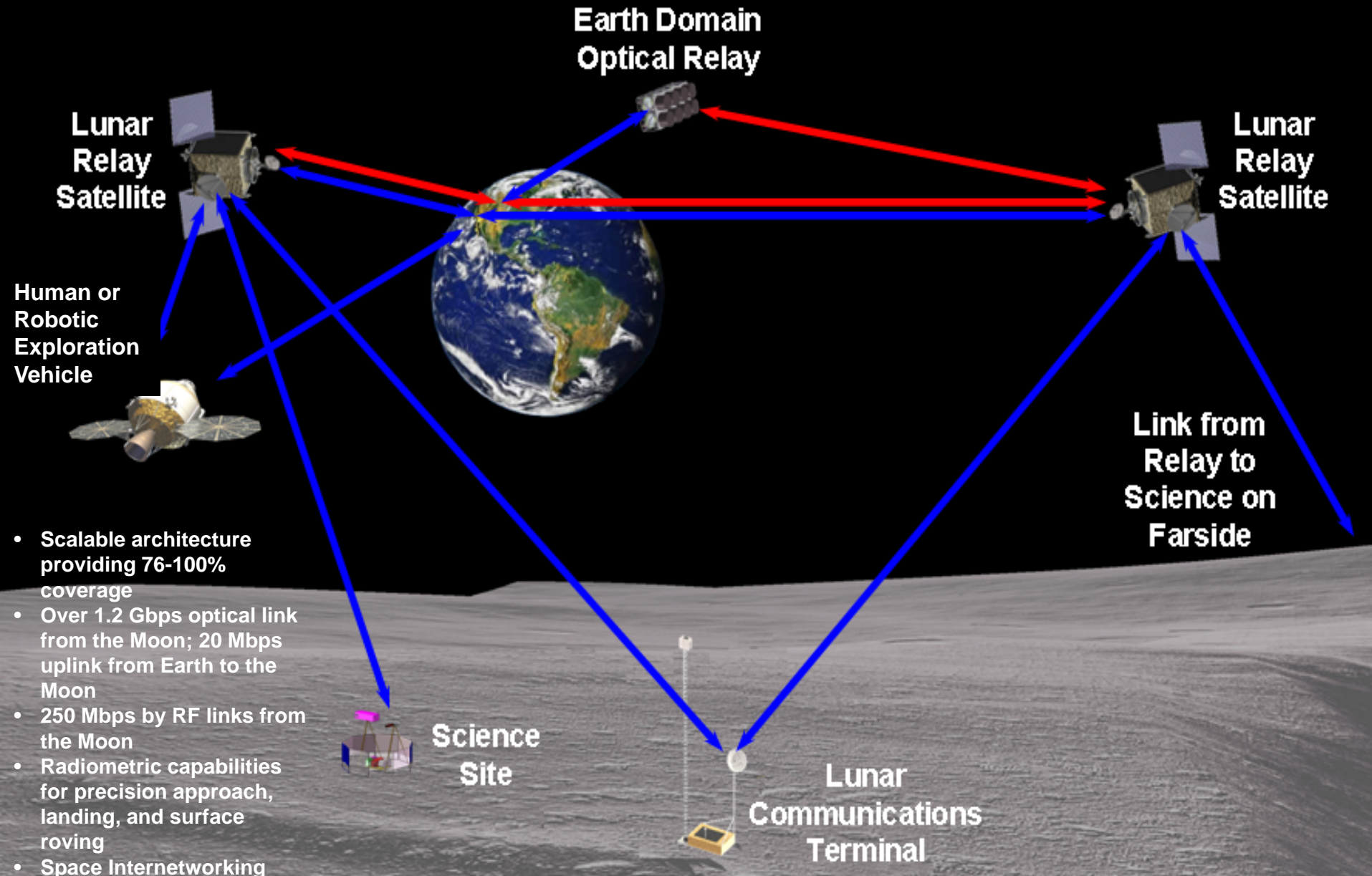
SCaN Services Provide:

- Integrated service-based architecture
- Space internetworking (DTN and IP)
- International interoperability
- Assured safety and security of missions
- Significant increases in bandwidth

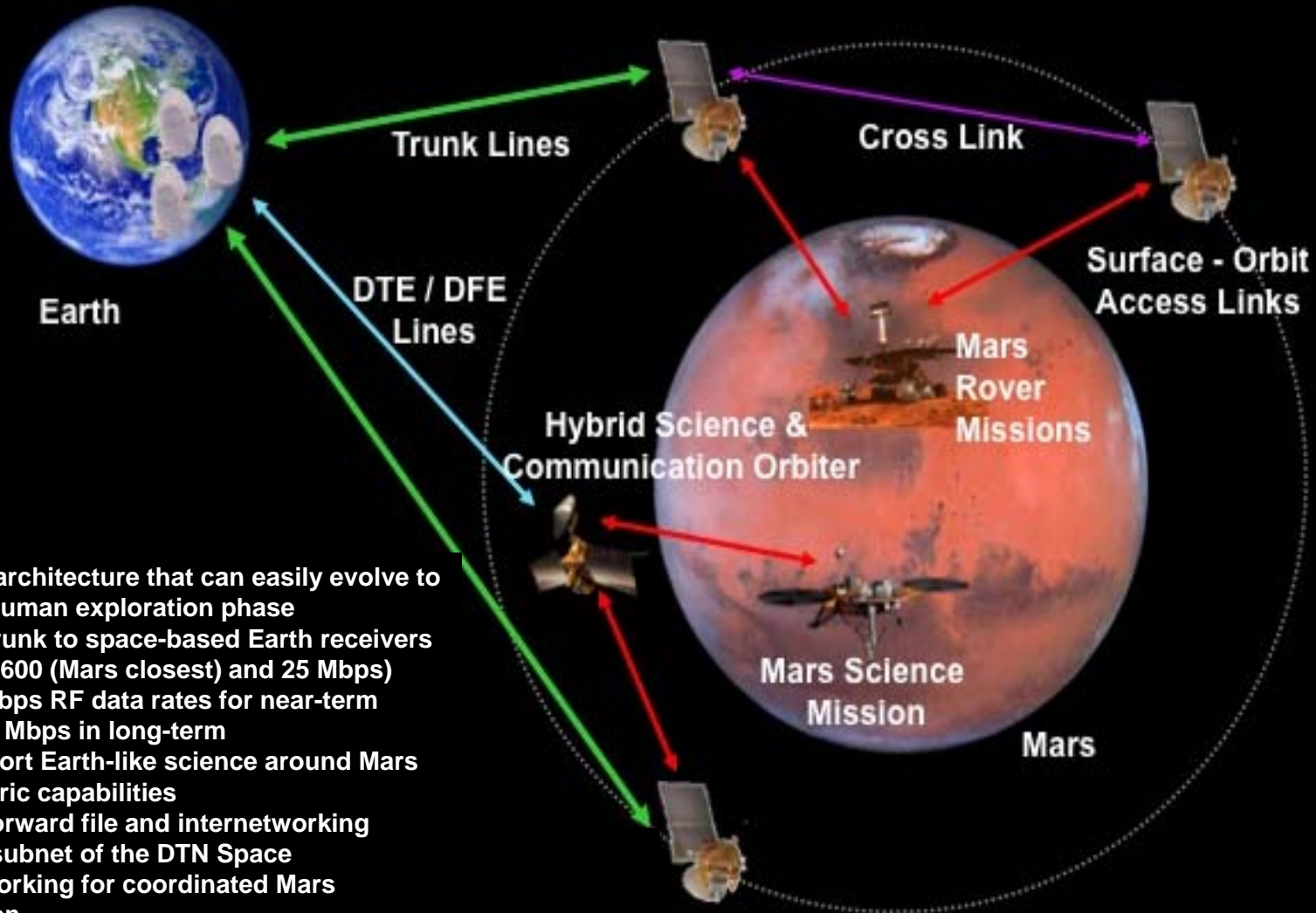
Enhanced Earth Domain Capabilities



Lunar Network



Mars Network



- Scalable architecture that can easily evolve to support human exploration phase
- Optical Trunk to space-based Earth receivers (between 600 (Mars closest) and 25 Mbps)
- Up to 2 Mbps RF data rates for near-term
- Up to 150 Mbps in long-term
- Can support Earth-like science around Mars
- Radiometric capabilities
- Store & forward file and internetworking
- Forms a subnet of the DTN Space Internetworking for coordinated Mars exploration

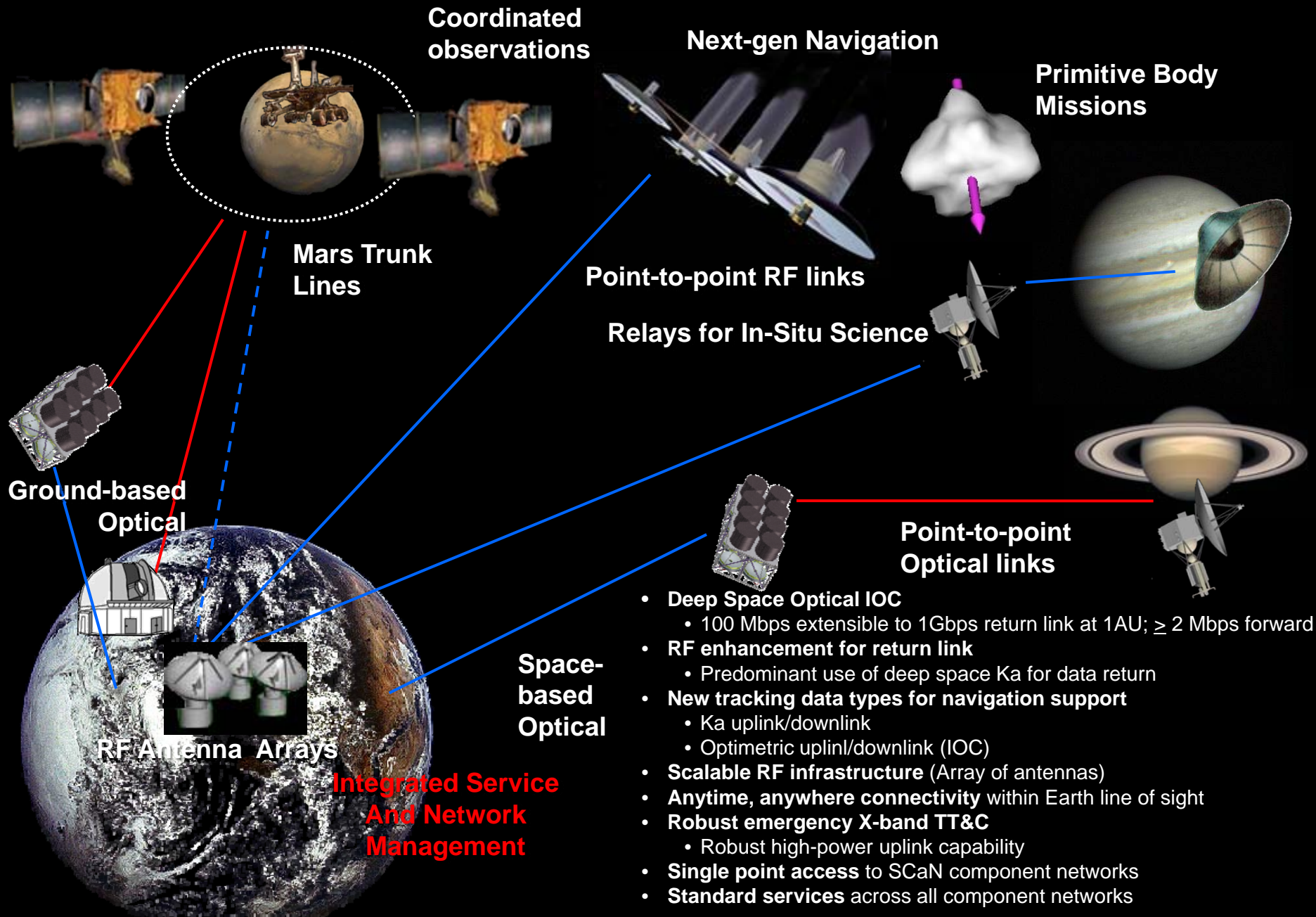
DTE/DFE Links

Access Links

Trunk Lines

Cross Links

Enhanced Deep Space Domain Capability





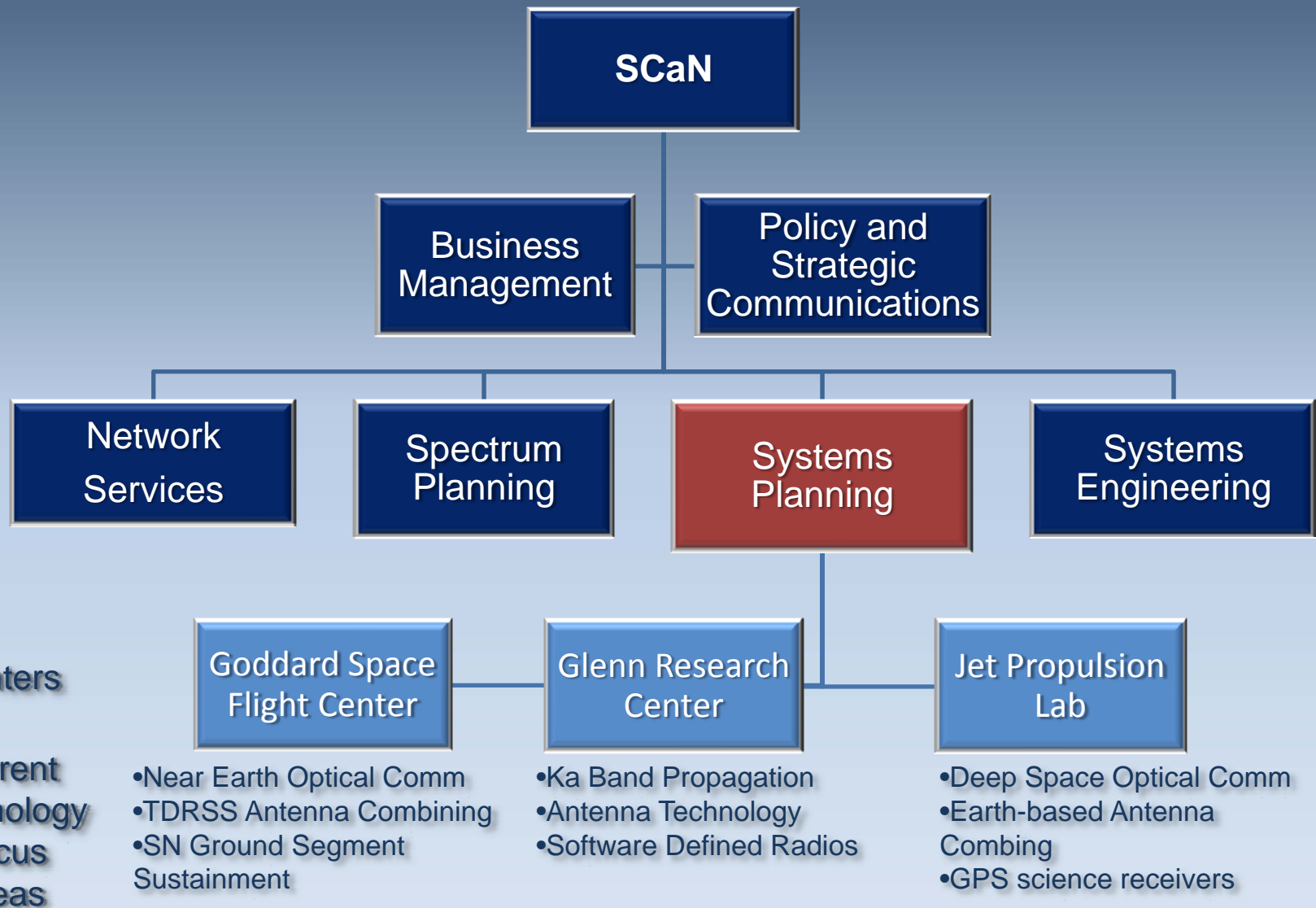
SCaN Technology

Goals of the SCaN Technology Program

- Support the SCaN Vision of the Future as Described in the SCaN Architecture Definition Document
- Enable Future NASA Missions with New Communication and Navigation Technology that Enhances their Science Return

SCaN Systems Planning

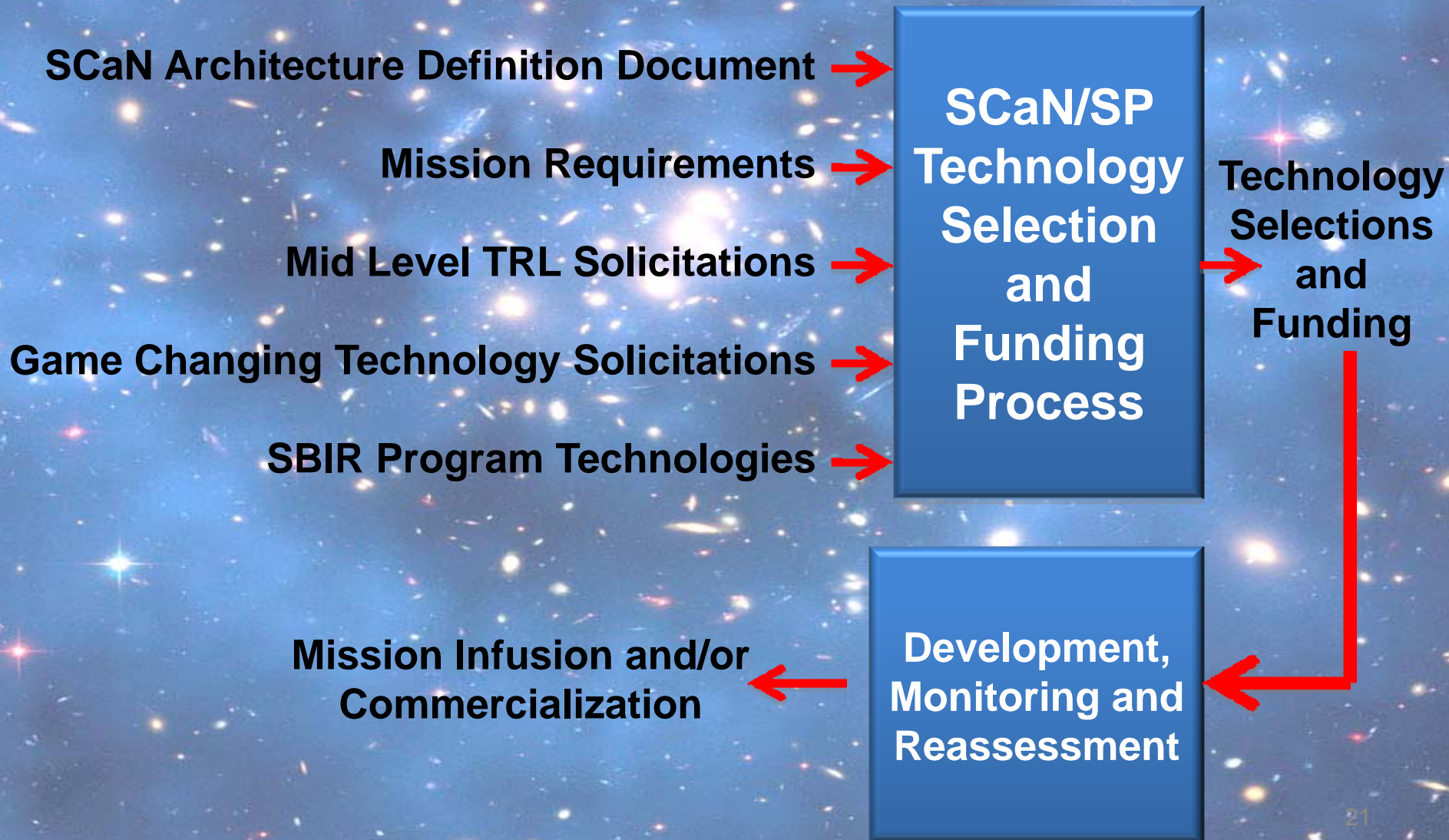
Oversees Development of Communication and Navigation Technologies



SCaN Funds Both “Pull” and “Push” Technologies

- A **Pull Technology** is one that is mission requirement driven, a technology needed to fulfill specific mission objective
 - e.g., a transceiver that provides a specific data rate required to fulfill a specified mission objective
- A **Push Technology** is one that is not directed to or required by a specific mission, but instead would provide a generic capability which could enable or enhance future missions
 - e.g., a high sensitivity receiver that could improve link capability by 20 db
- SBIR technologies may be either Pull or Push technologies

The SBIR Program is Integrated Into the SCaN Technology Selection, Development and Infusion Process



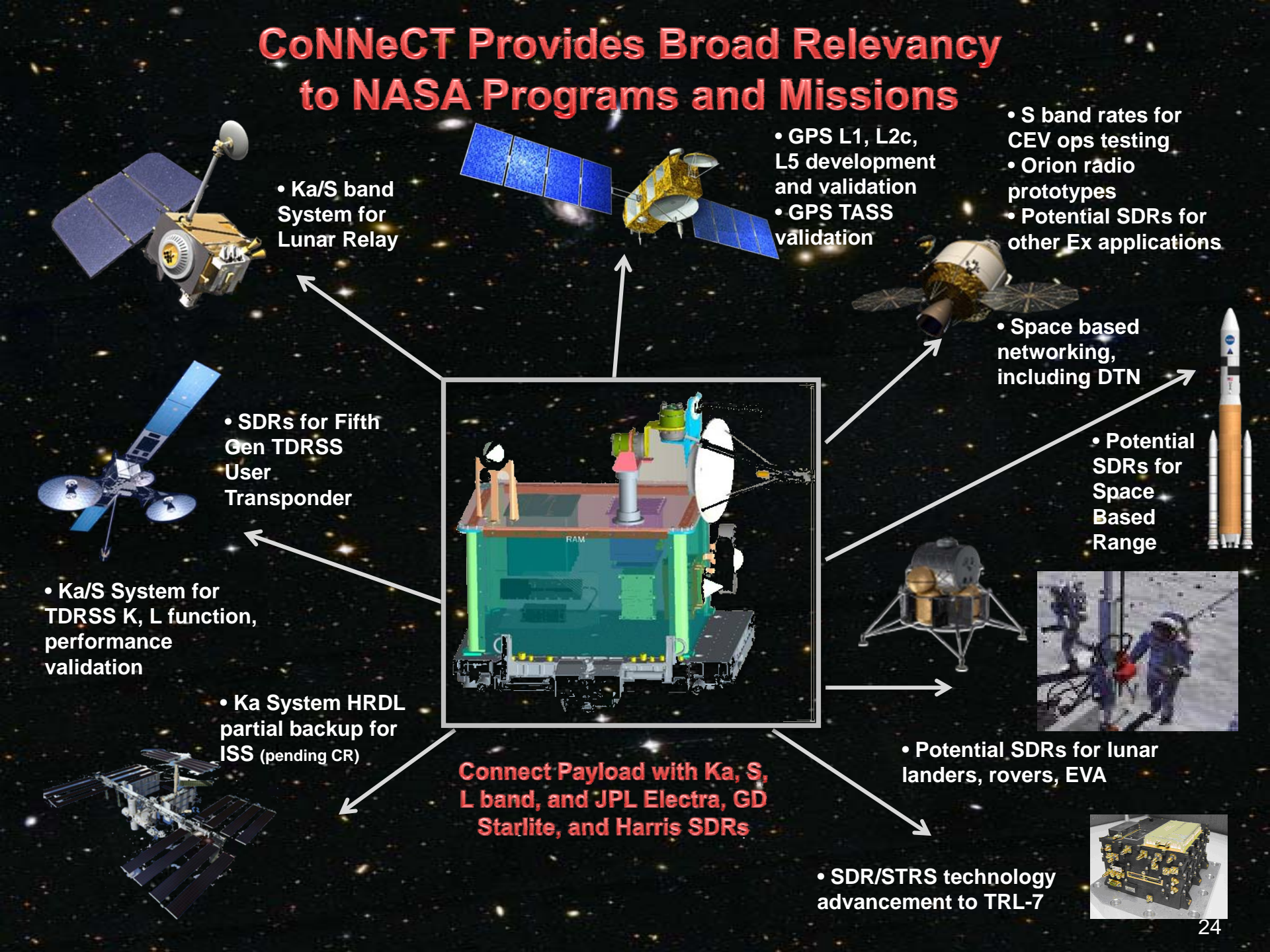
SCaN Communications and Navigation Technology Themes

- **Optical Communications**
- **Antenna Arraying Technology – Receive and Transmit**
- **Advanced Antenna Technology**
- **Advanced Networking Technology**
- **Spacecraft RF Transmitter/Receiver Technology**
- **Software Defined Radio**
- **Spacecraft Antenna Technology**
- **Spectrum Efficient Technology**
- **Ka-band Atmospheric Calibration**
- **Position, Navigation, and Time**
- **Space-Based Range Technology**
- **Uplink Arraying**

Why Use Software Defined Radios?

- SDRs provide unprecedented operational flexibility with software functionality that allows communications functions to be updated in flight
 - Functions can be changed within the same SDR across mission phases
 - E.g., Range Safety functions in launch phase, mission ops functions in mission phase
 - Technology upgrades can be made in flight
 - E.g., modulation methods upgrades, new coding schemes
 - Failure corrections can be effected in flight
 - E.g., MRO corrected EMI problem with SW update in transit to Mars using the Electra SDR
- Small size, weight, and power is achievable for all SDRs, esp mobile units (e.g., EVAs, rovers), similar to cell phones
 - SDRs have excellent potential for miniaturization compared to conventional radios
- Software defined functionality enables standard radios to be tailored for specific missions with reusable software
 - Similar to PCs running standard programs like Word and Excel, standardization enables common hardware platforms to run common reusable software across many missions
 - Cost reductions are realized with common hardware architecture, reusable software and risk avoidance

CoNNeCT Provides Broad Relevancy to NASA Programs and Missions

- 
- Ka/S band System for Lunar Relay

- GPS L1, L2c, L5 development and validation
- GPS TASS validation

- S band rates for CEV ops testing
- Orion radio prototypes
- Potential SDRs for other Ex applications

- Space based networking, including DTN

- Potential SDRs for Space Based Range

- Potential SDRs for lunar landers, rovers, EVA

- SDR/STRS technology advancement to TRL-7

- SDRs for Fifth Gen TDRSS User Transponder

- Ka/S System for TDRSS K, L function, performance validation

- Ka System HRDL partial backup for ISS (pending CR)

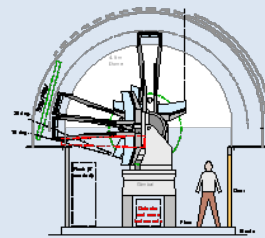
Connect Payload with Ka, S, L band, and JPL Electra, GD Starlite, and Harris SDRs

Optical Communications Technology

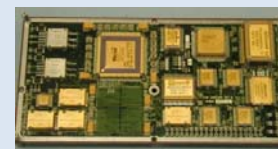
Objective

- Develop optical technologies for 10-1200 Megabit per second data links to meet NASA SCaN requirements for 2020 IOC

- Low mass and high efficiency implementations are required for deep space optical link scenarios
- Identify, develop, and validate high ROI ground and flight technologies
- Create the necessary technical infrastructure to test and validate industry and NASA developed optical communications flight components prior to flight



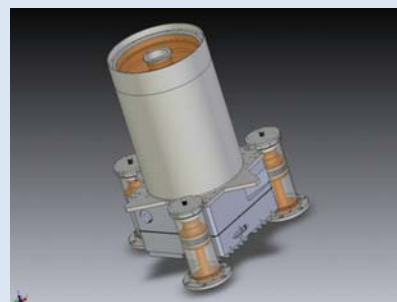
Ground Aperture



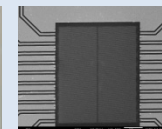
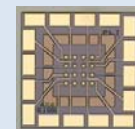
Optical Transceiver
Flight Processor



PPM Laser Transmitter



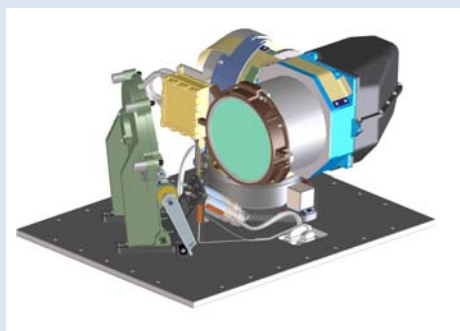
Deep Space Optical Transceiver



Single Photon Detectors



Scalable
Receiver/Decoder



Near Earth Ground
Terminal

Near Earth Flight
Terminal

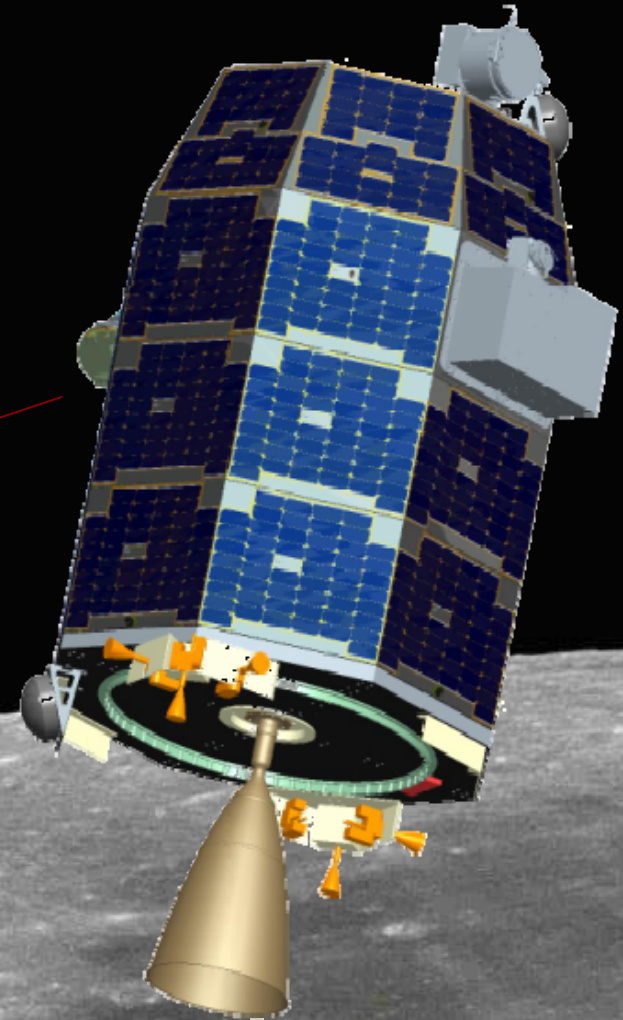


Some Example Key Challenges:

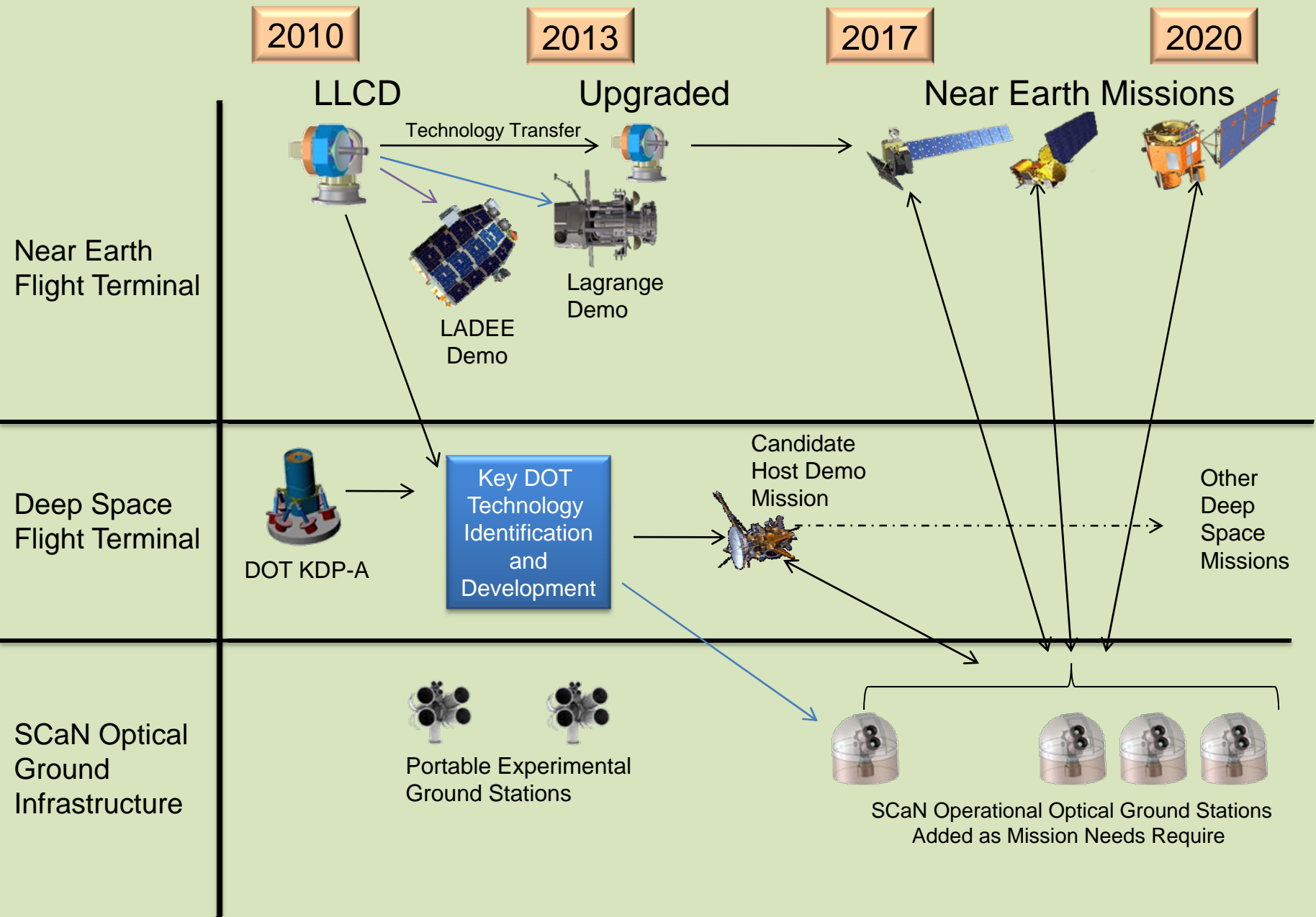
- Sub-Hertz vibration isolator; flight photon counting detector arrays
- Lightweight flight optics; integrated flight photon counting detector arrays with read-out integrated circuit
- Beaconless tracking solutions; high power uplink laser transmitter
- Detector jitter mitigation; efficient narrowband optical filter

Lunar Lasercom Space Terminal (LLST)

- Lunar Lasercom Space Terminal (LLST) to fly on Lunar Atmosphere and Dust Environment Explorer (LADEE)
- Launch Readiness Date: Mar 2013 from Wallops Flight Facility, VA on Minotaur V
 - 1 month transfer
 - 1 month commissioning
 - 250 km orbit
 - LLCD operation (up to 16 hours)
 - S/C and Science payloads checkout
 - 3 months science
 - 50 km orbit
 - 3 science payloads
 - Neutral Mass Spectrometer
 - UV Spectrometer
 - Lunar Dust Experiment



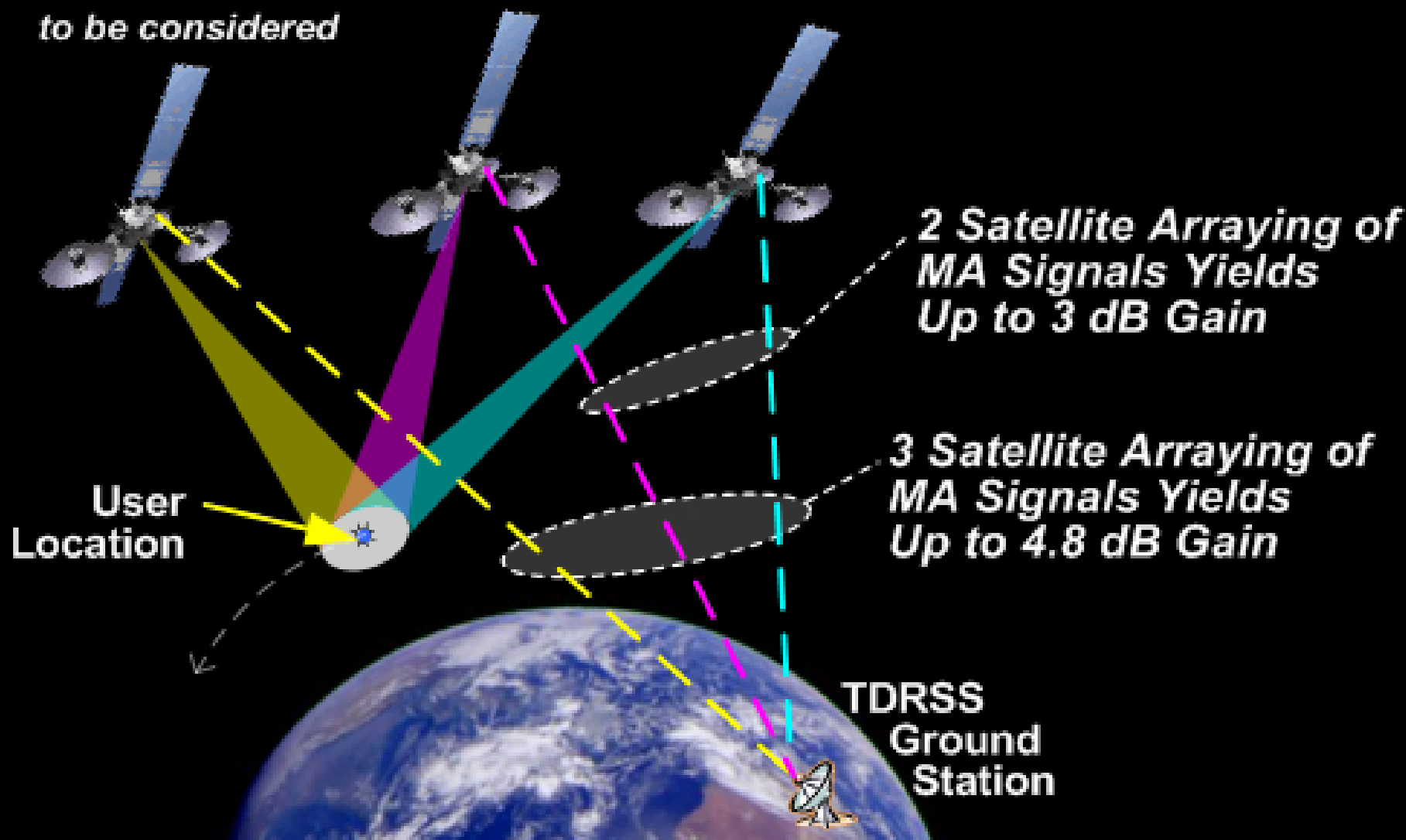
NASA Strategy for Optical Communication Development



TDRS Satellite Arraying Will Enhance Link Performance

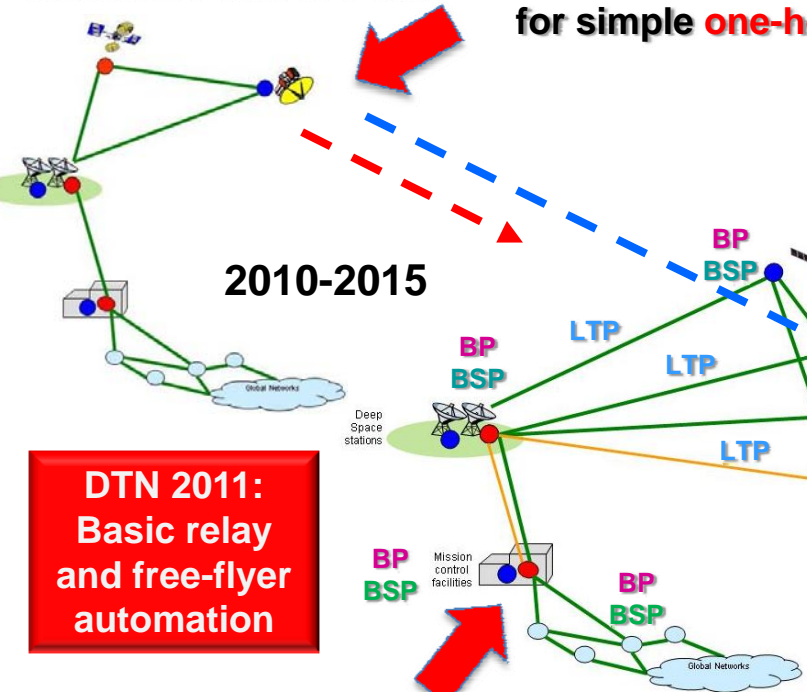
Two or More Relays per Node

Combinations of First and Second Generation TDRS to be considered



Phase-I of Space DTN Development

Classical Point-to-Point **AUTOMATION** of data transfer for simple **one-hop** missions



DTN 2011:
Basic relay
and free-flyer
automation

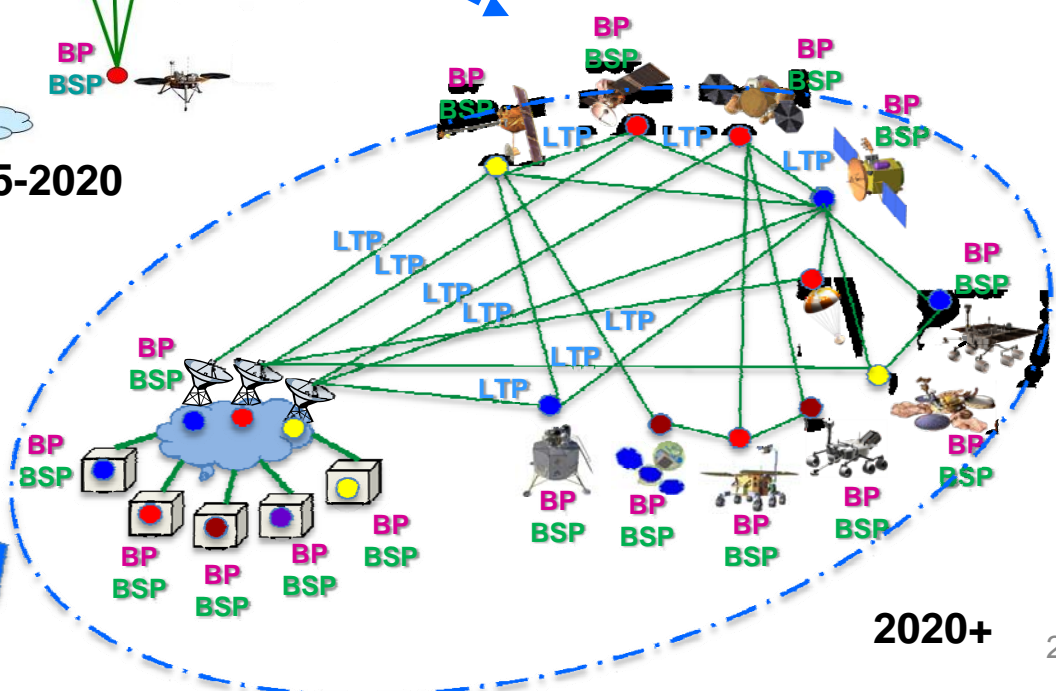
AUTOMATION of data transfer for emerging **multi-hop** missions

DTN 2016:
Solar System
Internet

FULLY AUTOMATED end-to-end operations of the Solar System Internet

Phase-II DTN

- DTN Applications** to support SSI user operations
- Quality of Service (QoS)** to support diversity
- Network Management** for monitor and control of the SSI
- Bundle Security Protocol (BSP)** in each node provides authentication
- Security** implemented end-to-end at multiple levels
- Security Key Management** for automated protection
- Network Time** distribution for synchronizing protocols
- Endpoint Naming** conventions for SSI address resolution
- Licklider Transport Protocol (LTP)** between nodes provides hop-by-hop reliability
- Routing** based on naming and late binding
- Multiple Access** to allow efficient resource sharing

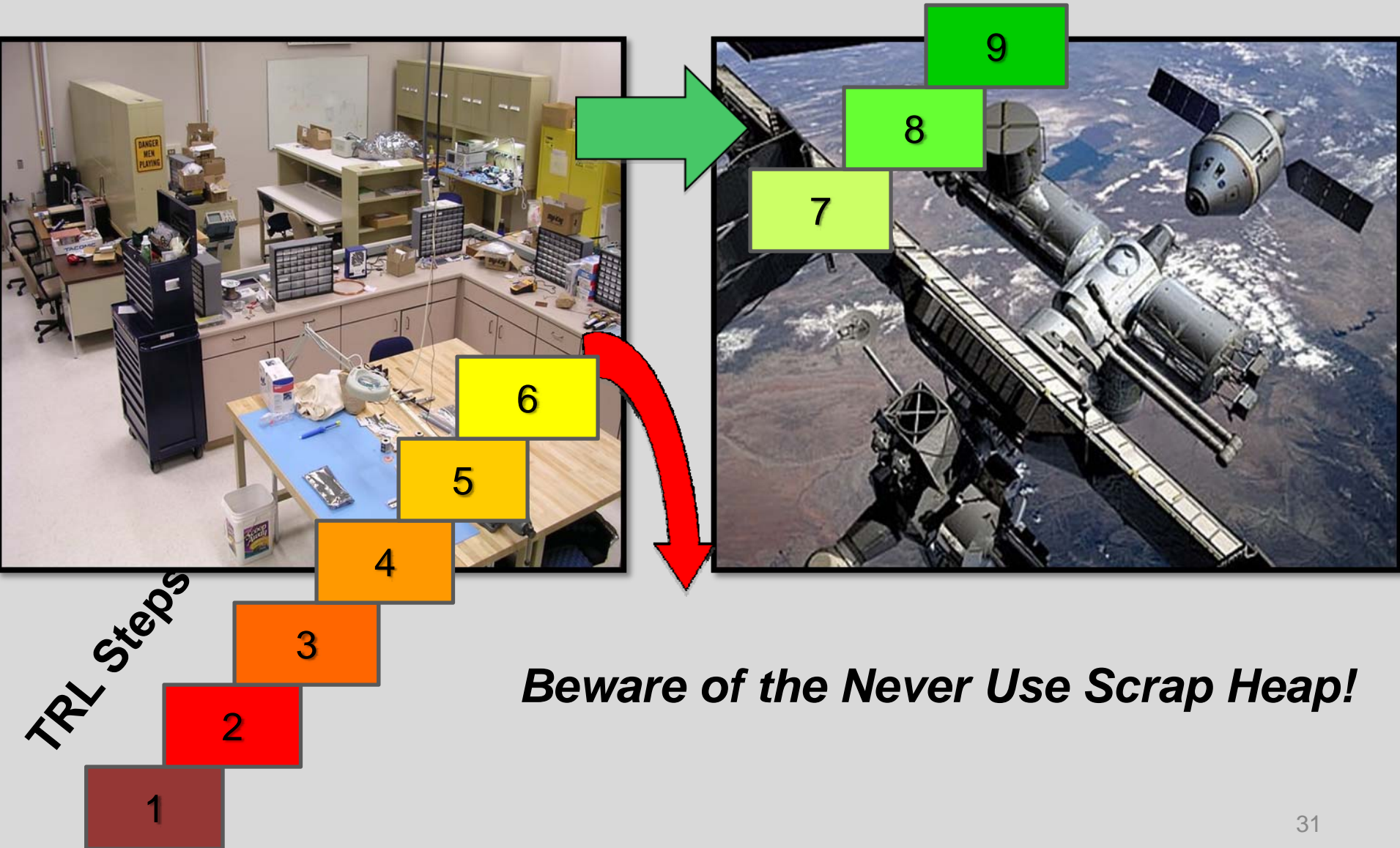


2020+

SCaN Funds Game Changing Technologies to Achieve Radical Improvements in Performance

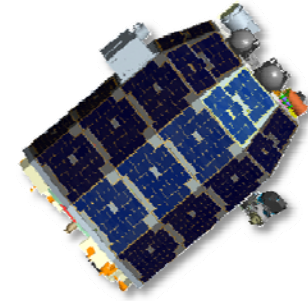
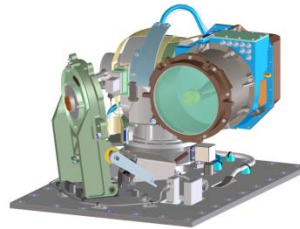
- Game Changing Technologies (GCT) offer the potential for improving comm. or nav. performance to the point that radical new mission objectives are possible
- GCTs are funded at low levels at first as progress and prognosis are monitored
- SCaN is currently funding three GCTs:
 - **Superconducting Quantum Interference Filters** may have the potential to improve receiver sensitivities by 60dB through detection of magnetic fields (GRC)
 - **Silicon Nanowire Optical Detectors** may provide a 10dB increase in single photon detection sensitivity (JPL)
 - **Auto-Configuring Cognitive Communications** embeds advanced decision making intelligence into communications and networking assets for improved levels of integration and flexible operations (GSFC)

The Transition From Ground-Based TRL 6 to Space Ops TRL 7 is a Major Step



SCaN Technologies Trying to Take the TRL 7 Leap

- Optical Communication



LADEE

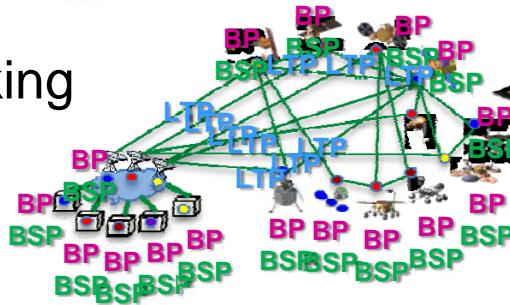
- Software Defined Radios



ISS



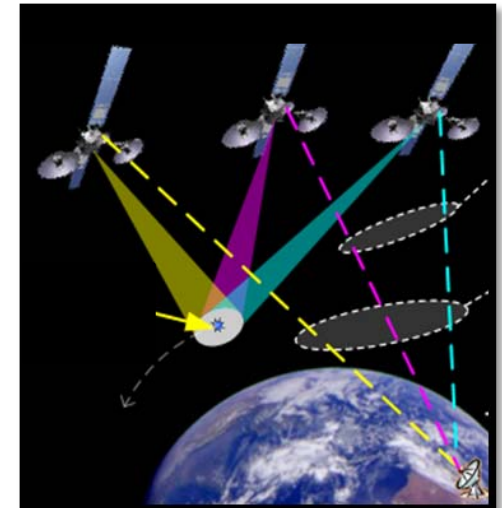
- Disruptive Tolerant Networking



- TDRSS Antenna Combining



TDRSS





For more information visit:
www.spacecomm.nasa.gov